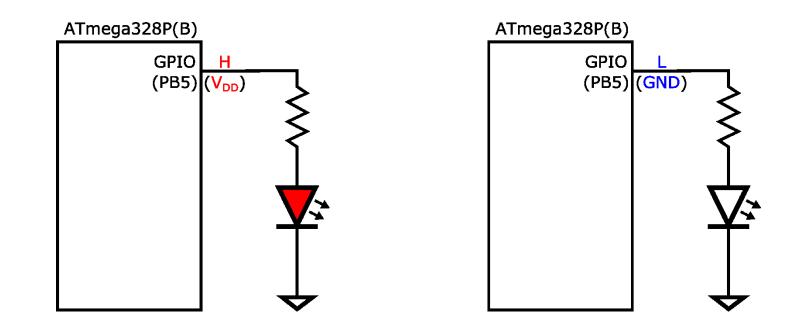
GPIO

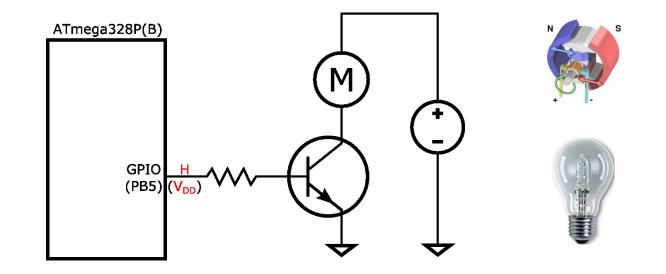
(General Purpose Inputs Outputs)

- General Purpose Input Output
 - Is used for input or output binary data from/to a device whose communication protocol is not standard.
 - > Each port pin can be individually selectable for input or output mode.
 - All port pins have individually selectable pull-up resistors with a supply-voltage invariant resistance.

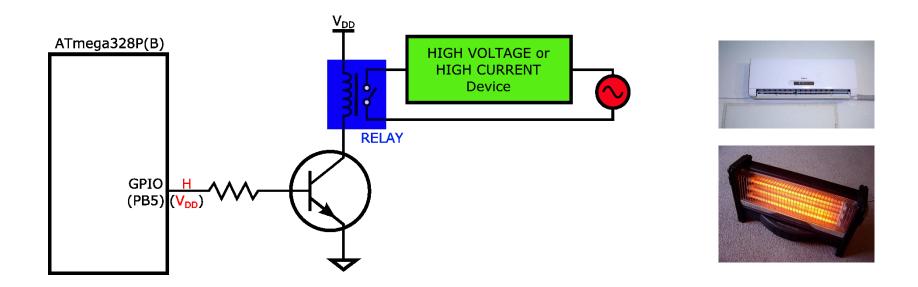
- General Purpose Output is used
 - > to control a device whose function is controlled by binary value, i.e. '0' or '1'.
 - > Examples: small dc power devices Turn on/off LEDs



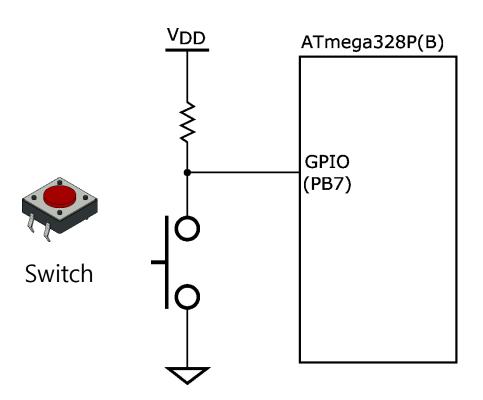
- General Purpose Output Example
 - > to control a device whose function is controlled by binary value, i.e. '0' or '1'.
 - > Example: medium or high dc power devices Turn on/off motors or lamps



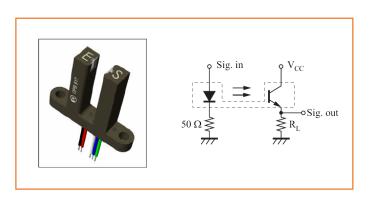
- General Purpose Output Example
 - > to control a device whose function is controlled by binary value, i.e. '0' or '1'.
 - > Example: low to high DC or AC power devices Turn on/off relays (heater, aircon)



- General Purpose Input is used
 - > to accept signal from a device whose output is binary value, i.e. '0' or '1'.
 - > Examples: switches

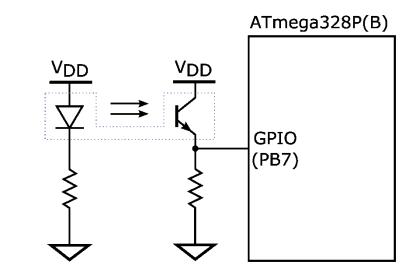


- General Purpose Input is used
 - > to accept signal from a device whose output is binary value, i.e. '0' or '1'.
 - > Examples: opto-interrupter, rotary encoder





Rotary Encoder



- General Purpose Input is used
 - > to accept signal from a device whose output is binary value, i.e. '0' or '1'.
 - > Examples: Hall-effect sensor, ultra-sonic sensor



GPIO Registers

DDRx register

- Data direction of GPIO pins

> PORTx register

Output data value

PINx register

• Input data value

| DDRx | DDRB | Bit No. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------------|------|-------------|------|------|------|------|------|------|------|------|
| x: Port name | | Name | DDB7 | DDB6 | DDB5 | DDB4 | DDB3 | DDB2 | DDB1 | DDBØ |
| DDRB, DDRC, DDRD | | Reset Value | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

> Determines data direction of GPIO pins

- $1 \rightarrow \text{Output}$
- $0 \rightarrow \text{Input}$

| Example: Port B | | | | | | | | | |
|-----------------------|---------|------|------|------|------|------|------|------|------|
| Bit 5 and 3: output | | | | | | | | | |
| Remaining bits: input | Bit No. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | Name | DDB7 | DDB6 | DDB5 | DDB4 | DDB3 | DDB2 | DDB1 | DDB0 |
| DDRB = 0b00101000; | Value | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 0 |

| PORTX | PORTB | Bit No. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------------------|-------|-------------|--------|--------|--------|--------|--------|--------|--------|--------|
| x: Port name | | Name | PORTB7 | PORTB6 | PORTB5 | PORTB4 | PORTB3 | PORTB2 | PORTB1 | PORTBØ |
| PORTB, PORTC, PORTD | | Reset Value | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

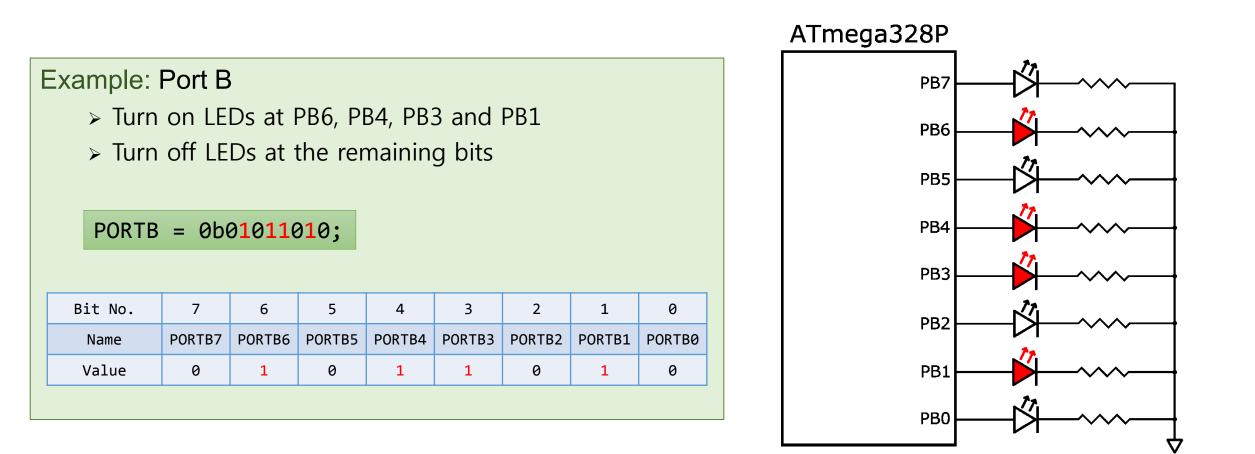
> Holds output data value of GPIO pins

- 1 \rightarrow High (V_{dd})
- $0 \rightarrow \text{Low}(\text{GND})$

Example: Port B > Bit 5: High, Bit 3: Low Bit No. 7 5 6 4 3 2 1 > Remaining bits: input PORTB7 PORTB6 PORTB5 PORTB4 PORTB3 PORTB2 PORTB1 **PORTBØ** Name PORTB = 0b0010000;Value 0 0 1 0 0 0 0

0

0



| PIN | x Re | aiste | ers |
|-----|------|-------|-----|
| | | 3.010 | |

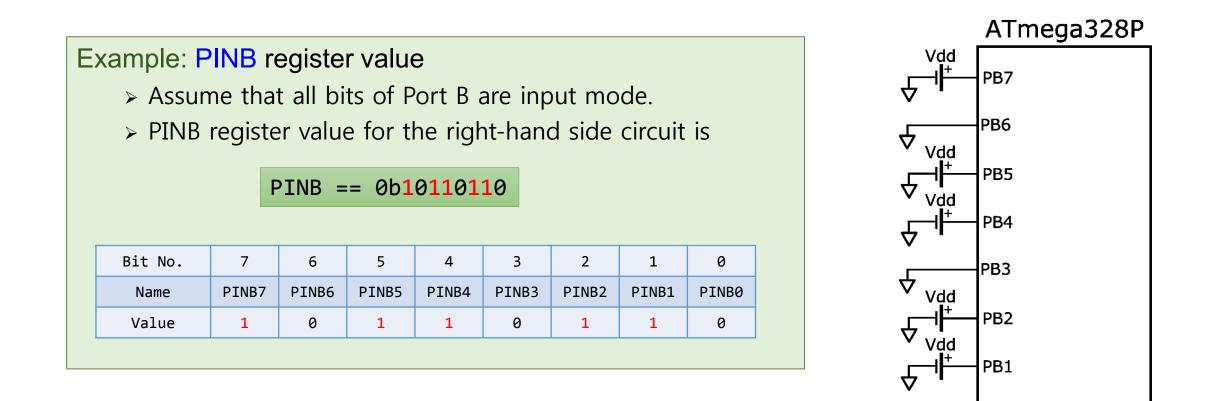
x: Port name

PINB, PINC, PIND

| Bit No. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|-------|-------|-------|-------|-------|-------|-------|-------|
| Name | PINB7 | PINB6 | PINB5 | PINB4 | PINB3 | PINB2 | PINB1 | PINBØ |
| Reset Value | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

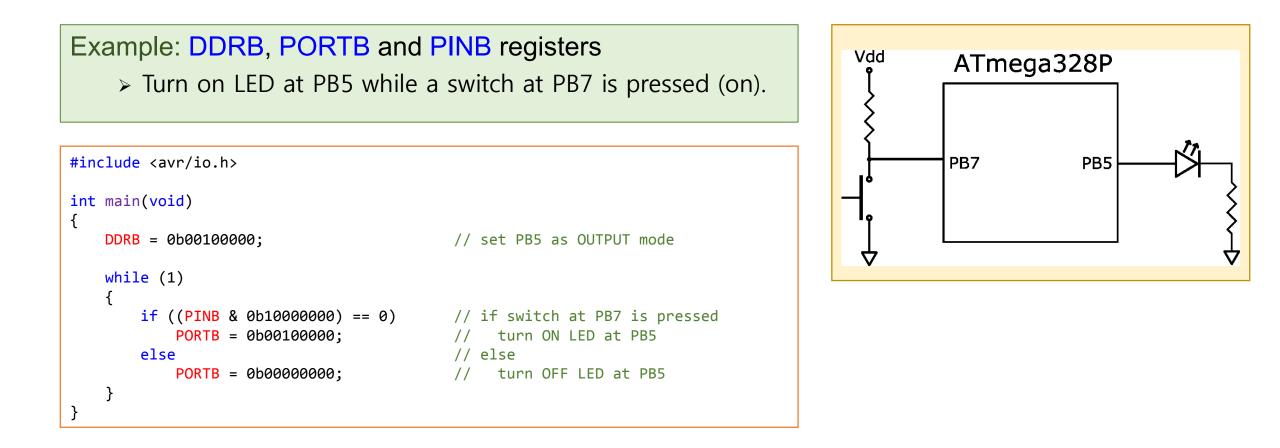
> Used to read input data value of GPIO pins

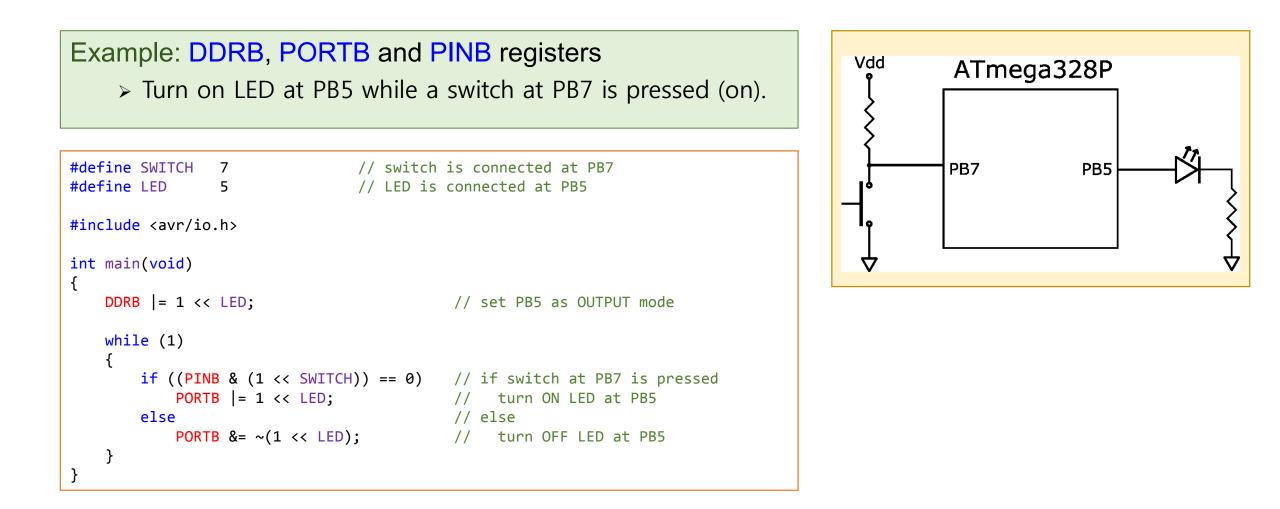
- High (V_{dd}) \rightarrow 1
- Low (GND) $\rightarrow 0$

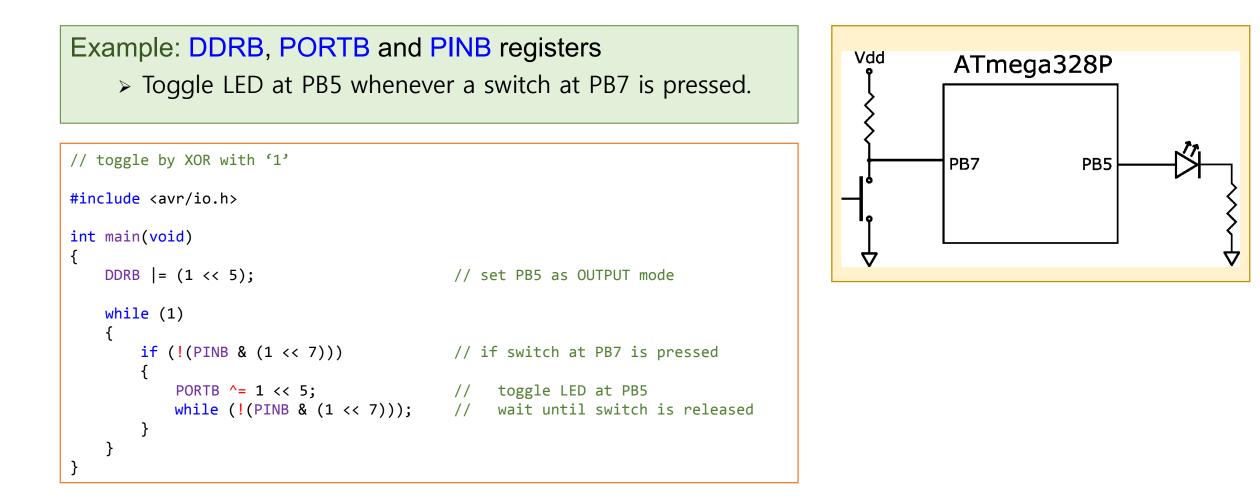


PB0

 Δ







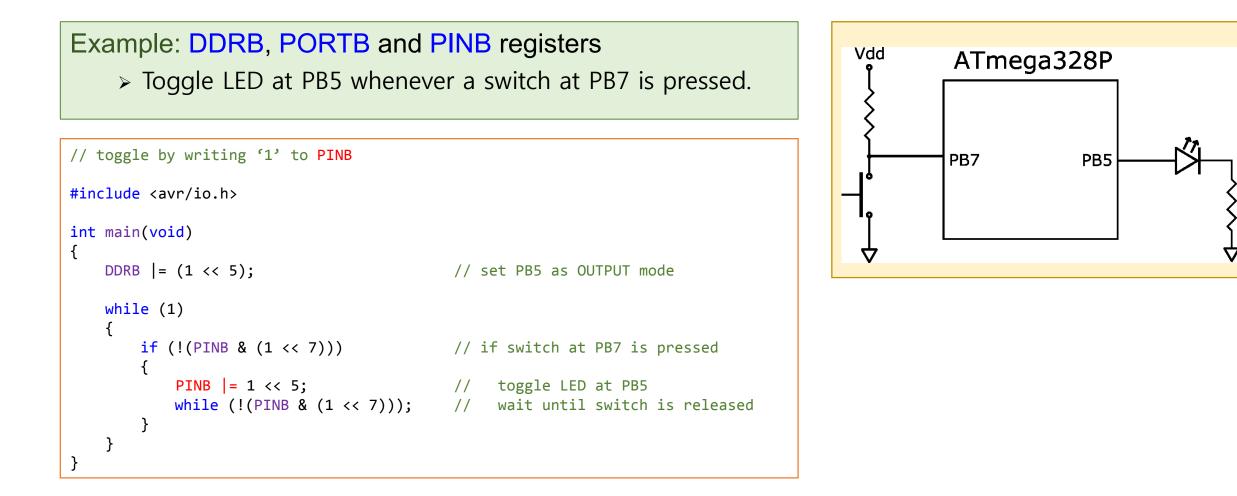
PINx Registers (used to toggle)

x: Port name

PINB, PINC, PIND

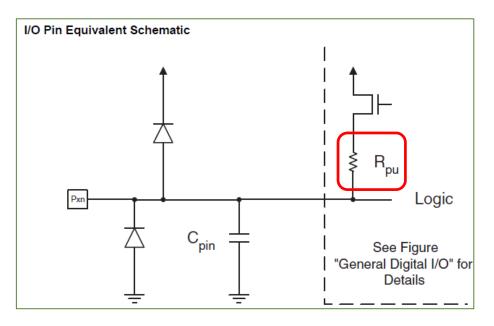
> Used to toggle data in the PORTx register

- Writing '1' to PINxn \rightarrow toggle n bit in the PORTx register
- Writing '0' to PINxn \rightarrow no change in the PORTx register

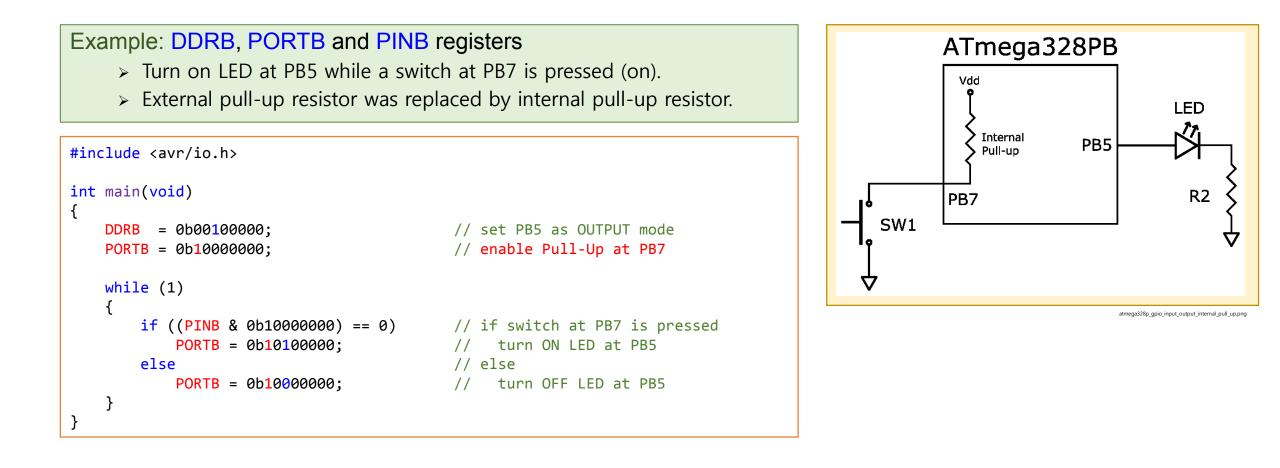


- Global pull-up control: PUD bit in MCUCR register
 - 0 → Pull-up enable
 - $1 \rightarrow \text{All pull-ups in the GPIO are disabled.}$

| MCUCR | | | | | | | | | |
|-------|----------------|---|------|-------|-----|---|---|-------|------|
| weeen | Bit No. | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | Name | - | BODS | BODSE | PUD | - | - | IVSEL | IVCE |
| | Reset Value | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |



- Individual pull-up control: each bit in PORTx register for input mode
 - $1 \rightarrow Pull-up enable$
 - $0 \rightarrow$ Pull-up in the GPIO pin is disabled.



• Symmetrical drive characteristics with both high sink and source capability.

> $I_{OH max}$ = 20mA at VCC = 5V, 10mA at VCC = 3V

- The sum of all IOH, for ports C0 C5, D0- D4, ADC7, RESET should not exceed 150mA.
- The sum of all IOH, for ports B0 B5, D5 D7, ADC6, XTAL1, XTAL2 should not exceed 150mA.

> $I_{OL max}$ = 20mA at VCC = 5V, 10mA at VCC = 3V

- The sum of all IOL, for ports C0 C5, ADC7, ADC6 should not exceed 100mA.
- The sum of all IOL, for ports B0 B5, D5 D7, XTAL1, XTAL2 should not exceed 100mA.
- The sum of all IOL, for ports D0 D4, RESET should not exceed 100mA.

ATmega328P GPIO Pin Driver Strength

Figure 35-22 ATmega328PB: I/O Pin Output Voltage vs. Sink Current (V_{CC} = 3V)

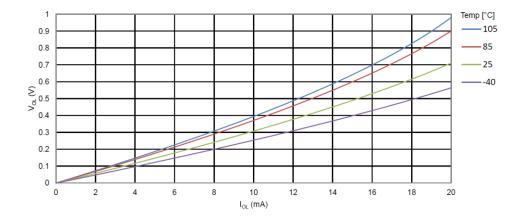


Figure 35-24 ATmega328PB: I/O Pin Output Voltage vs. Source Current (V_{CC} = 3V)

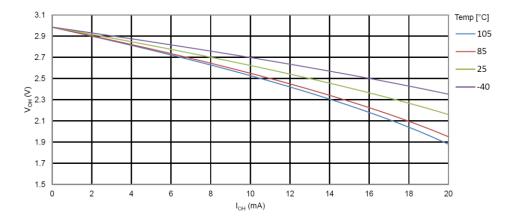


Figure 35-23 ATmega328PB: I/O Pin Output Voltage vs. Sink Current (V_{CC} = 5V)

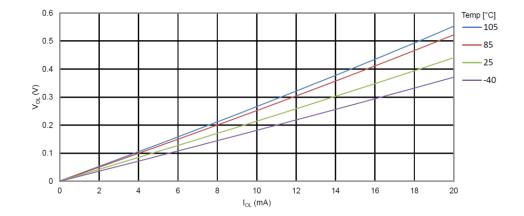
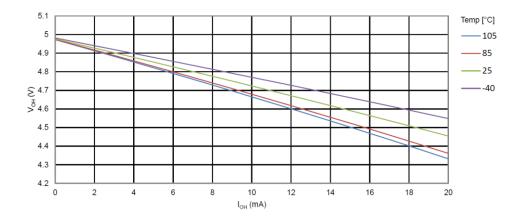


Figure 35-25 ATmega328PB I/O Pin Output Voltage vs. Source Current (V_{CC} = 5V)



What's next?



THE TWO STATES OF EVERY PROGRAMMER







I HAVE NO IDEA WHAT I'M DOING.